



A New Class of Parameter Shapes for Generalized iLUCK Models

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Institut
für
Statistik





Generalized iLUCK models

- ▶ a way to efficiently describe imprecise Bayesian inference by using sets of natural conjugate priors
- ▶ sets of priors defined via sets of canonical (hyper)parameters
 - $n^{(0)}, y^{(0)}$
 - ▶ $n^{(0)}$: pseudocounts, prior strength
 - ▶ $y^{(0)}$: prior guess on parameter of interest from sampling distr.



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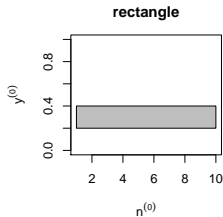
Imprecise Beta-Bernoulli/Binomial Model (IBBM)

Data :	s	\sim	$\text{Binom}(p, n)$
conjugate prior:	p	\sim	$\text{Beta}(n^{(0)}, y^{(0)})$
posterior:	$p \mid s$	\sim	$\text{Beta}(n^{(n)}, y^{(n)})$

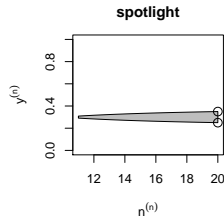

$$y^{(n)} = \frac{n^{(0)}}{n^{(0)} + n} \cdot y^{(0)} + \frac{n}{n^{(0)} + n} \cdot \frac{s}{n}, \quad n^{(n)} = n^{(0)} + n$$

Prior-Data Conflict and Set Shapes

- ▶ systematic reaction to prior-data conflict only with prior sets where $n^{(0)}$ varies.
- ▶ set shape has influence on prior-data conflict:

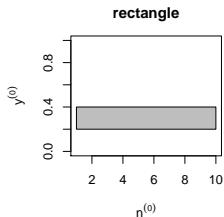


3 out of 10

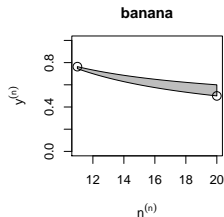



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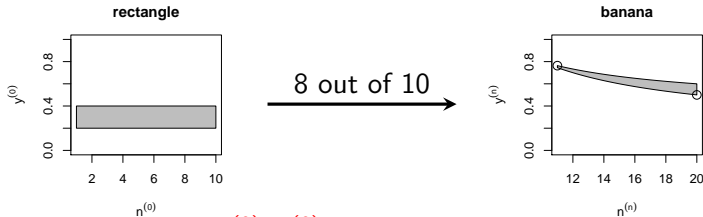


8 out of 10



Prior-Data Conflict and Set Shapes

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- ▶ when $s/n \notin [\underline{y}^{(0)}, \bar{y}^{(0)}]$, then additional imprecision.
- ▶ rectangle prior set is just first step, any shape is possible.
- ▶ take lower and upper borders as functions of $n^{(0)}$:
 $\underline{y}^{(0)}(n^{(0)}) / \bar{y}^{(0)}(n^{(0)})$, where $n^{(0)} \in [\underline{n}^{(0)}, \bar{n}^{(0)}]$
- ▶ define these functions by positions at left and right endpoints and a parameter to characterize the function in between.



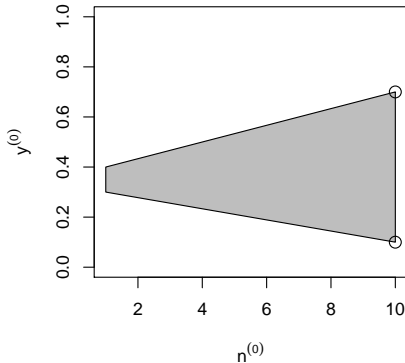
Precision of Elicitation Perspective

- ▶ for low $n^{(0)}$, can be precise with $y^{(0)}$ → short $y^{(0)}$ interval
- ▶ for high $n^{(0)}$, must be cautious with $y^{(0)}$ → long $y^{(0)}$ interval



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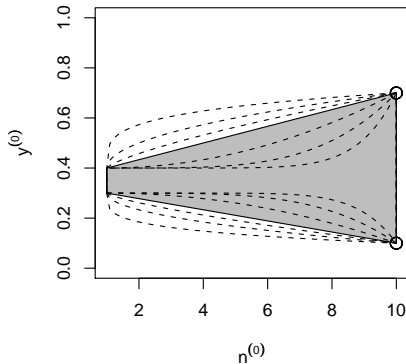
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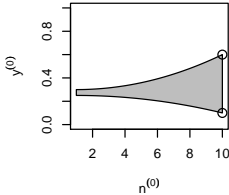
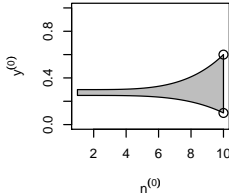
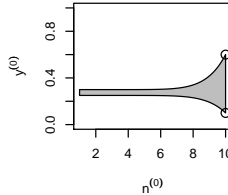
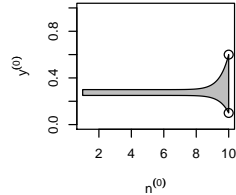
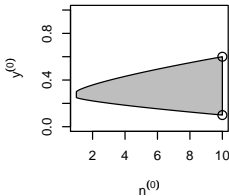
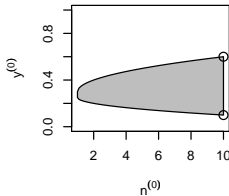
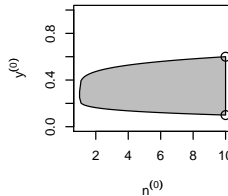
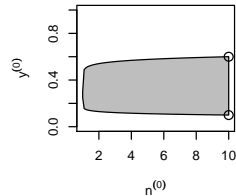
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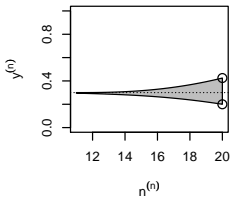
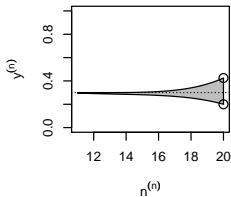
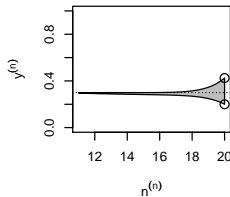
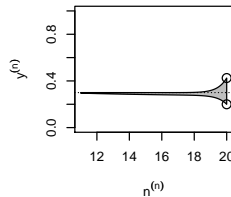
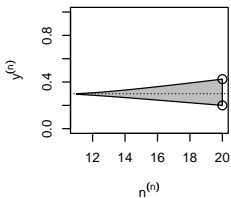
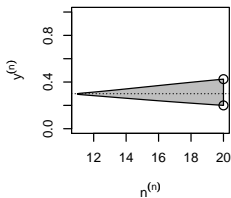
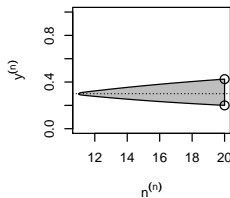
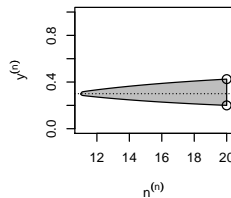


$$\begin{aligned}
 \bar{y}^{(0)}(n^{(0)}) &= \bar{y}_L^{(0)} + \left[\bar{y}_R^{(0)} - \bar{y}_L^{(0)} \right] \underbrace{\left(\frac{n^{(0)} - \underline{n}^{(0)}}{\bar{n}^{(0)} - \underline{n}^{(0)}} \right)^{\bar{\beta}}}_{=: \tilde{n}^{(0)}} \\
 &= \bar{y}_R^{(0)} \left[\tilde{n}^{(0)} \right]^{\bar{\beta}} + \bar{y}_L^{(0)} \left(1 - \left[\tilde{n}^{(0)} \right]^{\bar{\beta}} \right)
 \end{aligned}$$



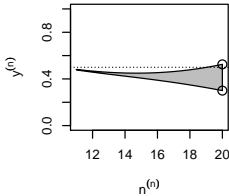
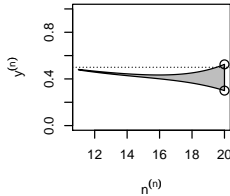
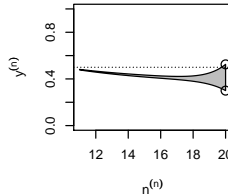
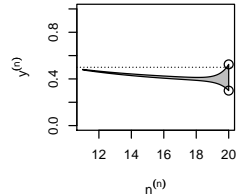
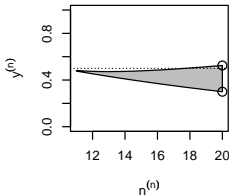
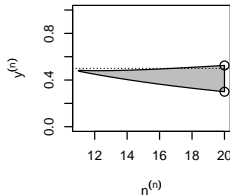
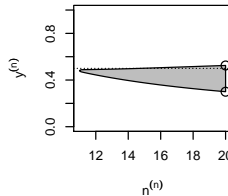
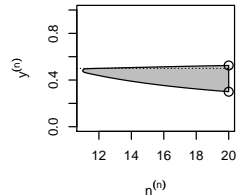
Precision of Elicitation Perspective: Priors

 $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 

Posteriors when $s/n = 3/10$ $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 



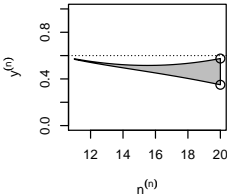
Posteriors when $s/n = 5/10$

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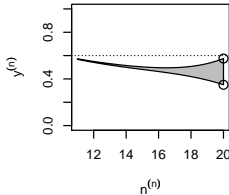


Posteriors when $s/n = 6/10$

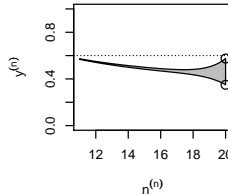
$\beta = 2$



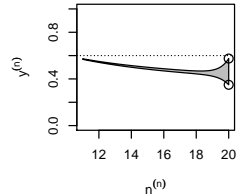
$\beta = 4$



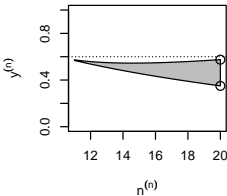
$\beta = 8$



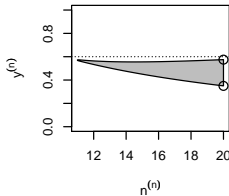
$\beta = 16$



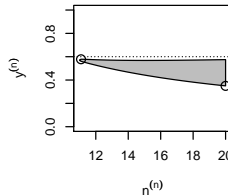
$\beta = 0.75$



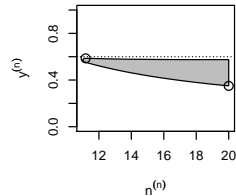
$\beta = 0.5$



$\beta = 0.25$

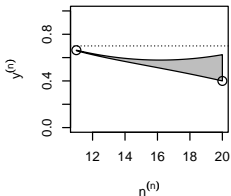
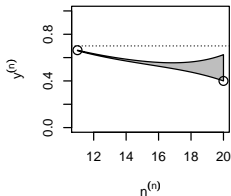
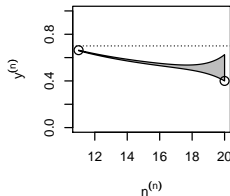
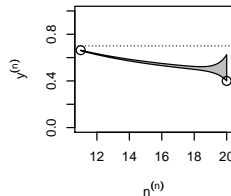
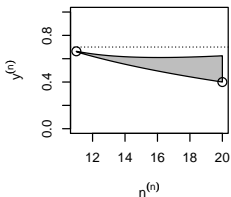
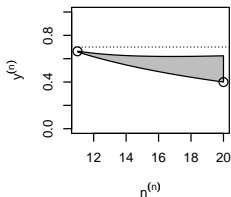
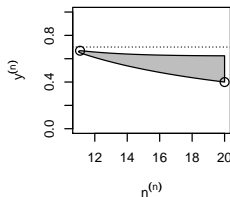
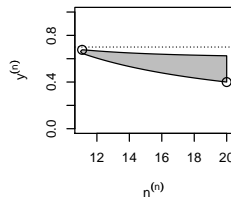


$\beta = 0.1$





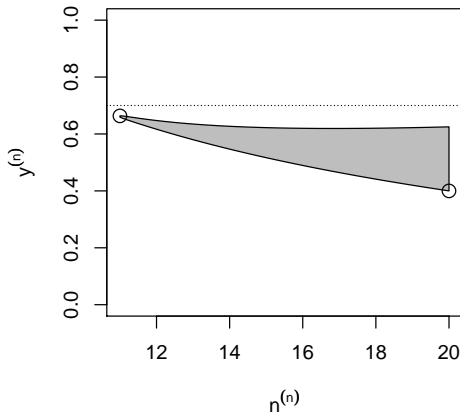
Posteriors when $s/n = 7/10$

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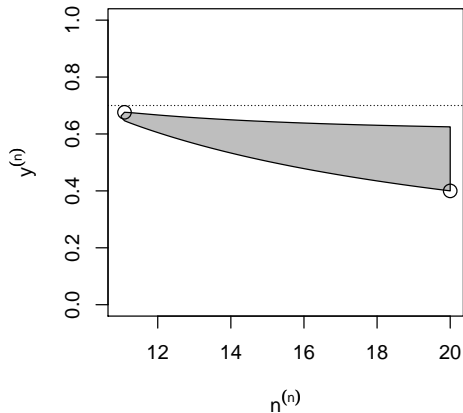


Posteriors when $s/n = 7/10$ — Zoom on $\beta = 0.5, 0.1$

$\beta = 0.5$



$\beta = 0.1$





Precision of Elicitation Perspective

- ▶ Sets with $\beta > 1$ show nice 'tolerance' behaviour: additional imprecision only when 'spike' at $\underline{n}^{(n)}$ overtakes $\bar{y}^{(n)}(\bar{n}^{(n)})$
- ▶ relatively easy updating rules, as expression for overtaking condition is fairly easy:



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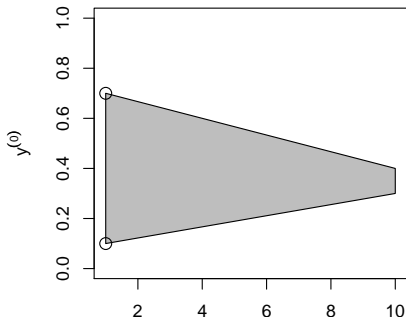
Velocity of Precision Increase Perspective

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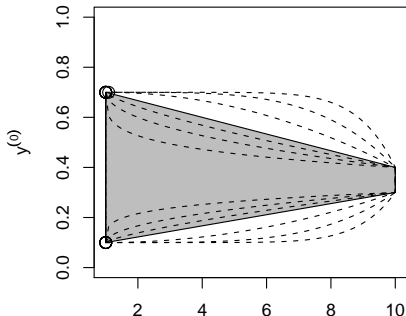
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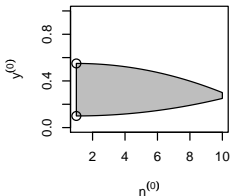
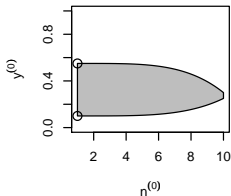
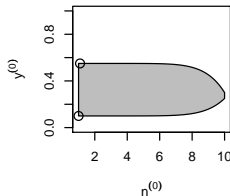
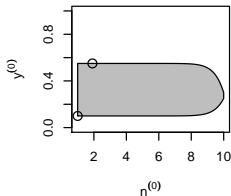
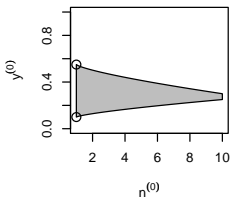
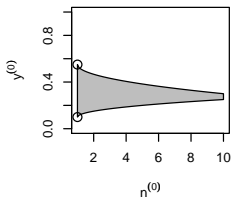
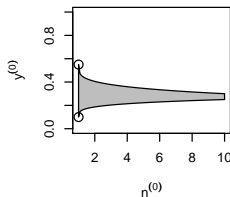
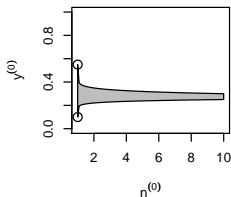
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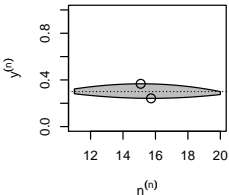
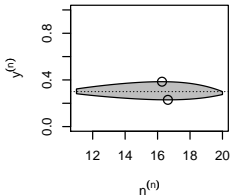
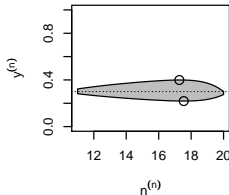
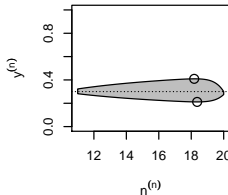
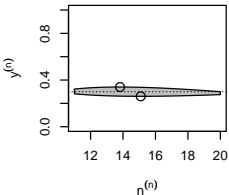
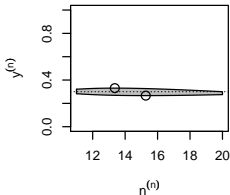
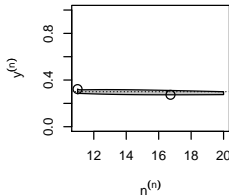
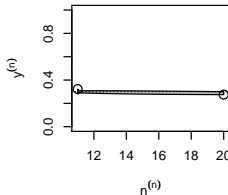


Velocity of Precision Increase Perspective: Priors

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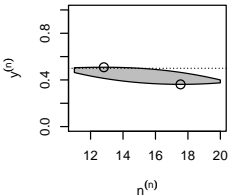
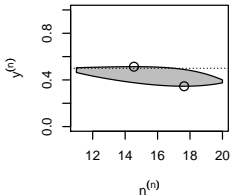
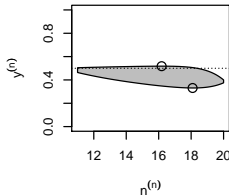
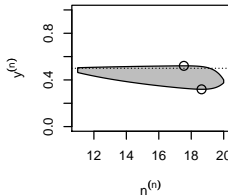
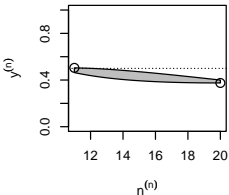
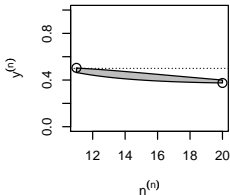
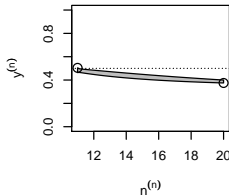
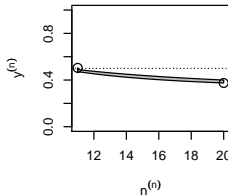


Posteriors when $s/n = 3/10$

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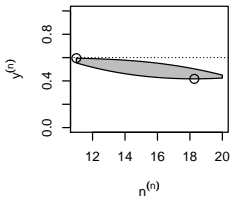
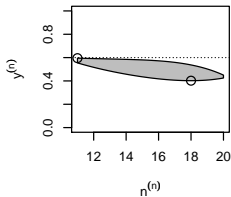
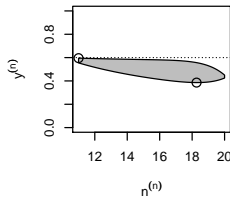
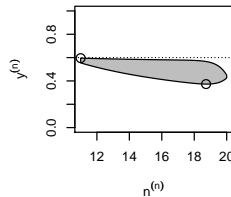
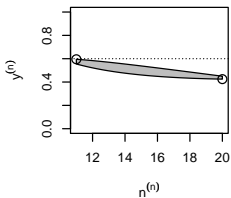
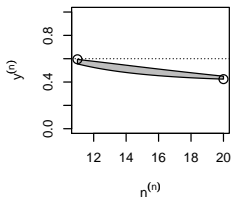
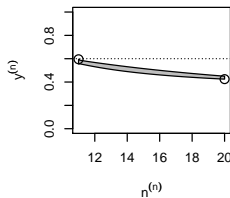
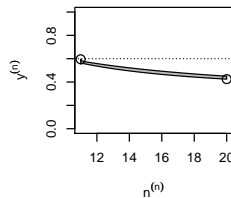


Posteriors when $s/n = 5/10$

 $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 

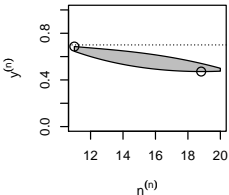
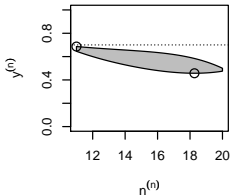
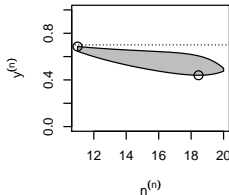
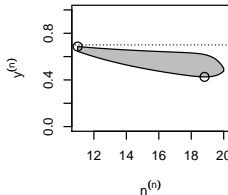
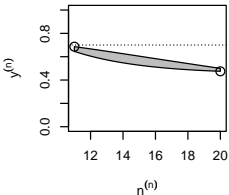
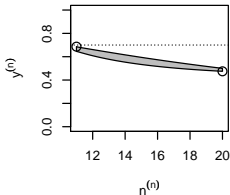
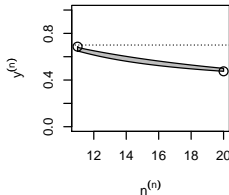
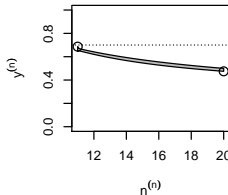


Posteriors when $s/n = 6/10$

 $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 



Posteriors when $s/n = 7/10$

 $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 

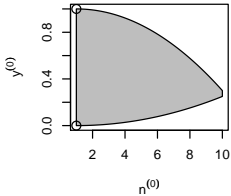
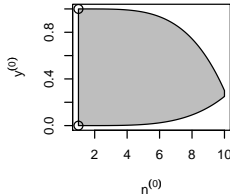
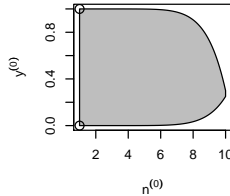
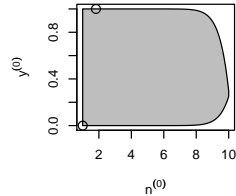
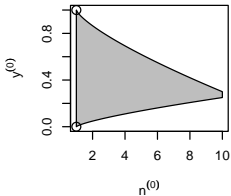
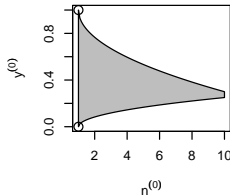
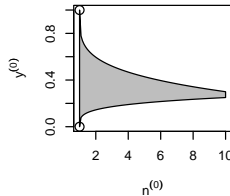
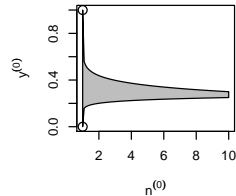


Velocity of Precision Increase Perspective

- ▶ for 'non-conflicting' observations, $\underline{y}^{(n)}$ and $\bar{y}^{(n)}$ are attained neither at $\underline{n}^{(0)}$ or $\bar{n}^{(0)}$.
- ▶ for 'conflicting' observations, nearest $y^{(n)}$ attained at $\underline{n}^{(0)}$ as for rectangle set. ($\beta > 1$: Fastest $y^{(n)}$ may stay away from $\underline{y}^{(n)}$ and $\bar{y}^{(n)}$.)
- ▶ Therefore no easily interpretable updating rules!
- ▶ 'picky' for $\beta < 1$, 'tolerance' reaction for $\beta > 1$.
- ▶ Does $[\underline{y}_L^{(0)}, \bar{y}_L^{(0)}] = [0, 1]$ makes sense?
(Would make elicitation easier.)

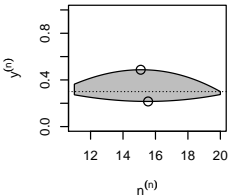
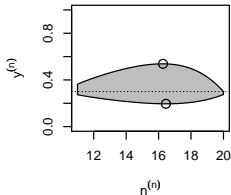
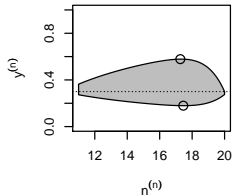
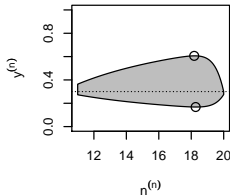
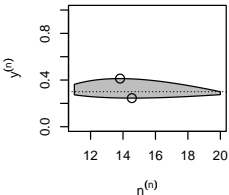
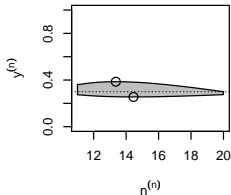
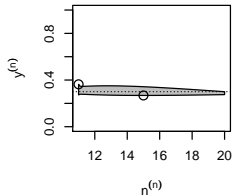
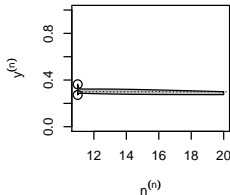


Velocity of Precision Increase Perspective: Priors

 $\beta = 2$  $\beta = 4$  $\beta = 8$  $\beta = 16$  $\beta = 0.75$  $\beta = 0.5$  $\beta = 0.25$  $\beta = 0.1$ 

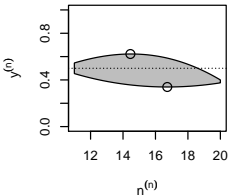
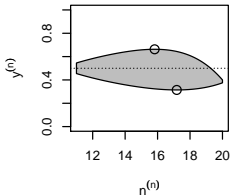
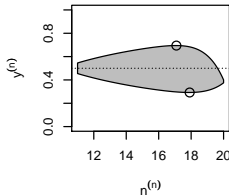
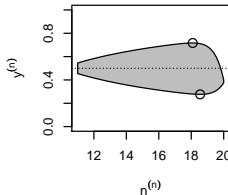
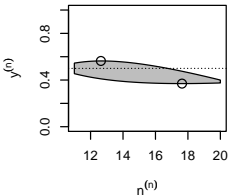
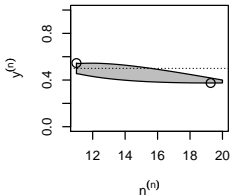
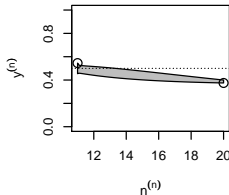
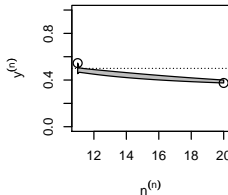


Posteriors when $s/n = 3/10$

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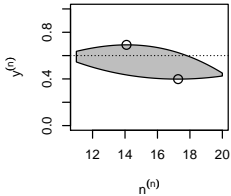
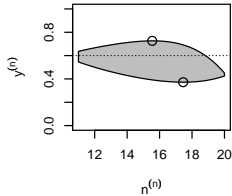
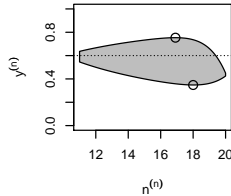
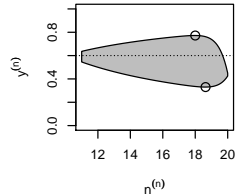
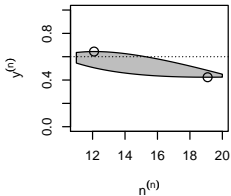
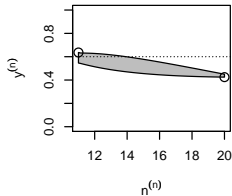
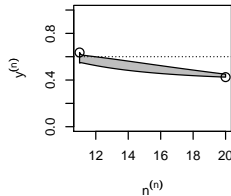
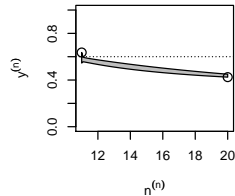


Posteriors when $s/n = 5/10$

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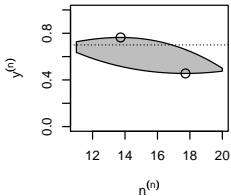
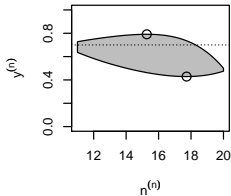
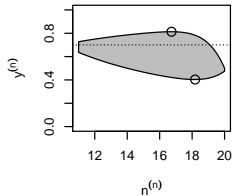
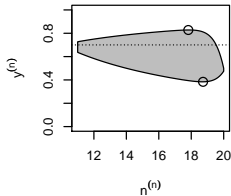
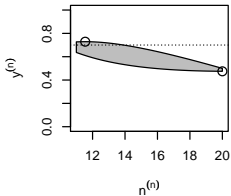
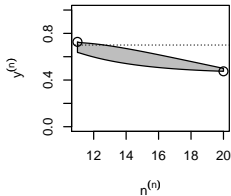
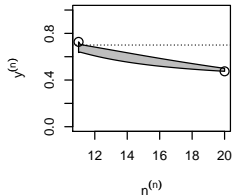
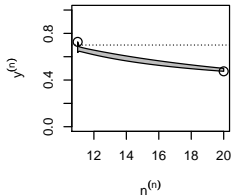


Posteriors when $s/n = 6/10$

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Further Questions

- ▶ Is there a shape description that is invariant to updating? (other than general subset, or with fixed $n^{(0)}$.)
- ▶ Is there a transformation of this parameter space that makes it easier to see what's going on?
- ▶ Look at Predictive Probability Plots (PPPs)
- ▶ ...