



The Effect of Prior-Data Conflict in Bayesian Linear Regression

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Prior-Data Conflict

Prior-Data Conflict $\hat{=}$ situation in which...

- ▶ ... informative prior beliefs and trusted data
(sampling model correct, no outliers, etc.) are in conflict
- ▶ "... the prior [places] its mass primarily on distributions in the sampling model for which the observed data is surprising."
(Evans & Moshonov, 2006)



Simple Example: Dirichlet-Multinomial-Model

Data:	\mathbf{k}	\sim	$M(\boldsymbol{\theta})$	$(\sum k_j = n)$
conjugate prior:	$\boldsymbol{\theta}$	\sim	$\text{Dir}(\boldsymbol{\alpha})$	$(\sum \theta_j = 1)$
posterior:	$\boldsymbol{\theta} \mathbf{k}$	\sim	$\text{Dir}(\boldsymbol{\alpha} + \mathbf{k})$	

$$\mathbb{E}[\theta_j] = \frac{\alpha_j}{\sum \alpha_i}$$

$$\text{V}(\theta_j) = \frac{\mathbb{E}[\theta_j](1 - \mathbb{E}[\theta_j])}{\sum \alpha_i + 1}$$



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$$\mathbb{E}[\theta_j] = \frac{\alpha_j}{\sum \alpha_i} =: y_j^{(0)} \quad \text{V}(\theta_j) = \frac{\mathbb{E}[\theta_j](1 - \mathbb{E}[\theta_j])}{\sum \alpha_i + 1} = \frac{y_j^{(0)}(1 - y_j^{(0)})}{n^{(0)} + 1}$$

Data :	\mathbf{k}	\sim	$M(\boldsymbol{\theta})$	
conjugate prior:	$\boldsymbol{\theta}$	\sim	$\text{Dir}(n^{(0)}, \mathbf{y}^{(0)})$	$n^{(0)} = \sum \alpha_i$
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Simple Example: Dirichlet-Multinomial-Model

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posterior:	$\theta \mathbf{k}$	\sim	$\text{Dir}(\alpha + \mathbf{k})$	

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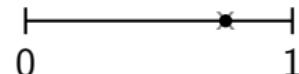
$$y_j^{(1)} = \frac{n^{(0)}}{n^{(0)} + n} \cdot y_j^{(0)} + \frac{n}{n^{(0)} + n} \cdot \frac{k_j}{n} \quad n^{(1)} = n^{(0)} + n$$



Simple Example: Dirichlet-Multinomial-Model

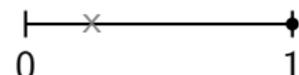
Case (i):

$$y_j^{(0)} = 0.75, \quad k_j/n = 0.75 \\ (n^{(0)} = 8) \quad \quad \quad (n = 16)$$



Case (ii):

$$y_j^{(0)} = 0.25, \quad k_j/n = 1 \\ (n^{(0)} = 8) \quad \quad \quad (n = 16)$$





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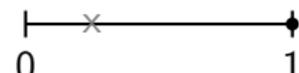
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$$\mathbb{E}[\theta_j | \mathbf{k}] = y_j^{(1)} = 0.75, \quad \mathbb{V}(\theta_j | \mathbf{k}) = 3/400$$



$$(\mathbb{V}(\theta_j) = 1/48)$$



Posterior inferences do not reflect uncertainty due to unexpected observations!





Conjugate Priors

Weighted average structure is underneath *all common conjugate priors* for exponential family sampling distributions!

$X \stackrel{iid}{\sim}$ linear, canonical exponential family, i.e.

$$p(x | \theta) \propto \exp \left\{ \langle \psi, \tau(x) \rangle - n \mathbf{b}(\psi) \right\} \quad [\psi \text{ transformation of } \theta]$$



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→ conjugate prior:

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→ (conjugate) posterior:

$$p(\theta | x) \propto \exp \{ n^{(1)} [\langle \psi, y^{(1)} \rangle - \mathbf{b}(\psi)] \},$$

where $y^{(1)} = \frac{n^{(0)}}{n^{(0)} + n} \cdot y^{(0)} + \frac{n}{n^{(0)} + n} \cdot \frac{1}{n} \tau(x)$ and $n^{(1)} = n^{(0)} + n$.



Bayesian Linear Regression

Are posterior inferences in Bayesian linear regression influenced by prior-data conflict?

$$z_i = x_i^T \beta + \varepsilon_i \quad [x_i \in \mathbb{R}^p, \beta \in \mathbb{R}^p]$$
$$z = \mathbf{X}\beta + \varepsilon$$



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$$z_i = x_i^T \beta + \varepsilon_i \quad [x_i \in \mathbb{R}^p, \beta \in \mathbb{R}^p] \quad \varepsilon_i \stackrel{iid}{\sim} N(0, \sigma^2)$$

$$z = \mathbf{X}\beta + \varepsilon \quad \rightarrow \quad z \mid \beta, \sigma^2 \sim N(\mathbf{X}\beta, \sigma^2 \mathbf{I})$$



Bayesian Linear Regression

Are posterior inferences in Bayesian linear regression influenced by prior-data conflict?

$$\begin{aligned} z_i &= x_i^T \beta + \varepsilon_i \quad [x_i \in \mathbb{R}^p, \beta \in \mathbb{R}^p] & \varepsilon_i &\stackrel{iid}{\sim} N(0, \sigma^2) \\ z &= \mathbf{X}\beta + \varepsilon & \rightarrow z | \beta, \sigma^2 &\sim N(\mathbf{X}\beta, \sigma^2 \mathbf{I}) \end{aligned}$$

Prior on (β, σ^2) : generally taken as $p(\beta, \sigma^2) = p(\beta | \sigma^2)p(\sigma^2)$.

- ▶ SCP: standard conjugate prior model (e.g., O'Hagan 1994)
- ▶ CCCP: “canonically constructed conjugate prior”



Standard Conjugate Prior (SCP)

$\beta \mid \sigma^2 \sim N_p(m^{(0)}, \sigma^2 \mathbf{M}^{(0)})$ (multivariate Normal)

$\sigma^2 \sim IG(a^{(0)}, b^{(0)})$ (Inverse Gamma, e.g. $p(\sigma^2) \propto \frac{e^{-\frac{b^{(0)}}{\sigma^2}}}{(\sigma^2)^{a^{(0)}+1}}$)



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$$m^{(1)} = \left(\mathbf{M}^{(0)-1} + \mathbf{X}^\top \mathbf{X} \right)^{-1} \left(\mathbf{M}^{(0)-1} m^{(0)} + \mathbf{X}^\top z \right)$$

$$\mathbf{M}^{(1)} = \left(\mathbf{M}^{(0)-1} + \mathbf{X}^\top \mathbf{X} \right)^{-1}$$

$$a^{(1)} = a^{(0)} + \frac{n}{2}$$

$$b^{(1)} = b^{(0)} + \frac{1}{2} \left(z^\top z + m^{(0)\top} \mathbf{M}^{(0)-1} m^{(0)} - m^{(1)\top} \mathbf{M}^{(1)-1} m^{(1)} \right)$$



SCP: Update step for $\beta \mid \sigma^2$

$$\mathbb{E}[\beta \mid \sigma^2] = m^{(0)}$$

$$\mathbb{E}[\beta \mid \sigma^2, z] = m^{(1)} = (\mathbf{I} - \mathbf{A}) m^{(0)} + \mathbf{A} \hat{\beta}^{\text{LS}}$$

$$\text{where } \mathbf{A} = (\mathbf{M}^{(0)-1} + \mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X}$$

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$$\mathbb{V}(\beta \mid \sigma^2) = \sigma^2 \mathbf{M}^{(0)}$$

$$\mathbb{V}(\beta \mid \sigma^2, z) = \sigma^2 \mathbf{M}^{(1)} = \sigma^2 \left(\mathbf{M}^{(0)-1} + \mathbf{X}^T \mathbf{X} \right)^{-1}$$

$$\rightarrow \mathbb{V}(\beta_j \mid \sigma^2, z) < \mathbb{V}(\beta_j \mid \sigma^2)$$



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$$\rightarrow \mathbb{V}(\beta_j \mid \sigma^2, z) < \mathbb{V}(\beta_j \mid \sigma^2)$$

Actually of interest:

$$\mathbb{E}[\beta] = m^{(0)}, \quad \mathbb{V}(\beta) = \frac{b^{(0)}}{a^{(0)} - 1} \mathbf{M}^{(0)} = \mathbb{E}[\sigma^2] \mathbf{M}^{(0)}$$

$$\mathbb{E}[\beta \mid z] = m^{(1)}, \quad \mathbb{V}(\beta \mid z) = \frac{b^{(1)}}{a^{(1)} - 1} \mathbf{M}^{(1)} = \mathbb{E}[\sigma^2 \mid z] \mathbf{M}^{(1)}$$



SCP: Update step for σ^2

$$\mathbb{E}[\sigma^2 | z] = \frac{2a^{(0)} - 2}{2a^{(0)} + n - 2} \mathbb{E}[\sigma^2] + \frac{n - p}{2a^{(0)} + n - 2} \hat{\sigma}_{\text{LS}}^2 + \frac{p}{2a^{(0)} + n - 2} \hat{\sigma}_{\text{PDC}}^2$$

$$\hat{\sigma}_{\text{LS}}^2 = \frac{1}{n - p} (z - \mathbf{X}\hat{\beta}^{\text{LS}})^T (z - \mathbf{X}\hat{\beta}^{\text{LS}})$$

$$\hat{\sigma}_{\text{PDC}}^2 = \frac{1}{p} (m^{(0)} - \hat{\beta}^{\text{LS}})^T (\mathbf{M}^{(0)} + (\mathbf{X}^T \mathbf{X})^{-1})^{-1} (m^{(0)} - \hat{\beta}^{\text{LS}})$$

$$\rightarrow \mathbb{E}[\hat{\sigma}_{\text{PDC}}^2 | \sigma^2] = \sigma^2$$



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➡ $\mathbb{E}[\hat{\sigma}_{\text{PDC}}^2 | \sigma^2] = \sigma^2$

Weights:

- ▶ $2a^{(0)} - 2$ for $\mathbb{E}[\sigma^2]$: think of $\mathbb{V}(\sigma^2) = \frac{(b^{(0)})^2}{(a^{(0)} - 1)^2(a^{(0)} - 2)}$
- ▶ $n - p$ for $\hat{\sigma}_{\text{LS}}^2$: usual *dfs* in least-squares estimate
- ▶ p for $\hat{\sigma}_{\text{PDC}}^2$: $\dim(\beta)$ = number of dimensions in which prior-data conflict is possible



SCP: Summary

$$\mathbb{E}[\beta \mid z] = m^{(1)}$$

$$\mathbb{V}(\beta \mid z) = \mathbb{E}[\sigma^2 \mid z] \cdot \mathbf{M}^{(1)}$$



SCP: Summary

weighted average of prior and LS estimate

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may increase due to
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diagonal strictly decreasing:
 $\mathbb{V}(\beta_j | \sigma^2, z) < \mathbb{V}(\beta_j | \sigma^2)$



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→ Posterior variance may increase due to prior-data conflict. But:



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weighted average of prior and LS estimate

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$$\mathbb{V}(\beta | z) = \mathbb{E}[\sigma^2 | z] \cdot \mathbf{M}^{(1)}$$

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diagonal strictly decreasing:
 $\mathbb{V}(\beta_j | \sigma^2, z) < \mathbb{V}(\beta_j | \sigma^2)$

→ Posterior variance may increase due to prior-data conflict. But:

- ▶ Effect of possible increase of $\mathbb{E}[\sigma^2 | z]$ contrasted by automatic decrease of $\mathbf{M}^{(1)}$!
- ▶ Variance increase *by the same factor* for all β_j !



Canonically Constructed Conjugate Prior (CCCP)

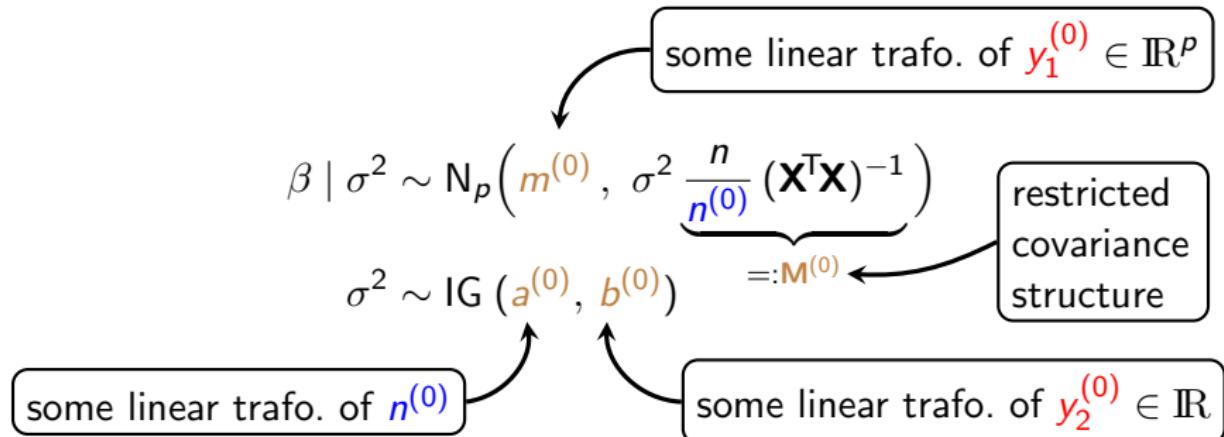
CCCP turns out as a special case of SCP:

$$\begin{aligned}\beta \mid \sigma^2 &\sim N_p\left(\textcolor{brown}{m^{(0)}}, \sigma^2 \underbrace{\frac{n}{n^{(0)}} (\mathbf{X}^\top \mathbf{X})^{-1}}_{=: \mathbf{M}^{(0)}}\right) \\ \sigma^2 &\sim \text{IG}(\textcolor{brown}{a^{(0)}}, \textcolor{brown}{b^{(0)}})\end{aligned}$$



Canonically Constructed Conjugate Prior (CCCP)

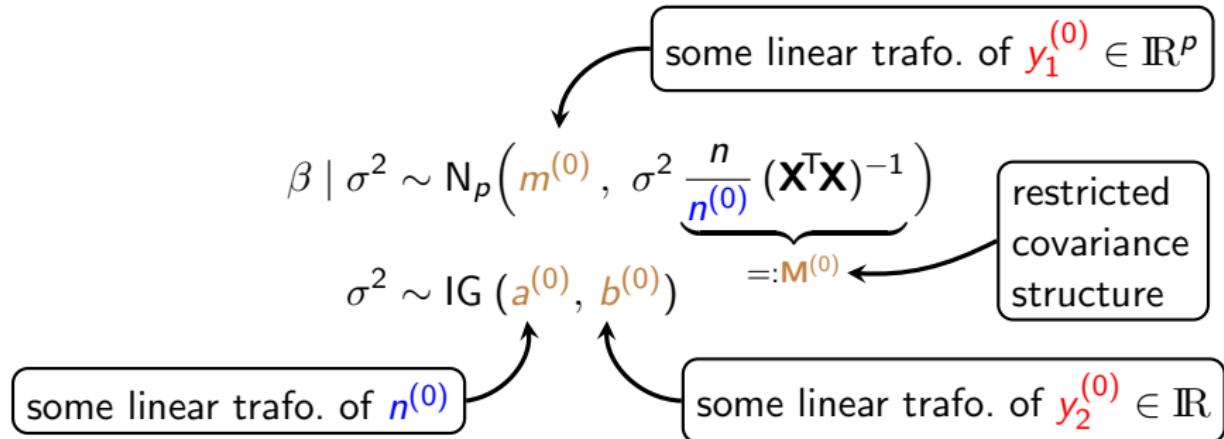
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CCCP turns out as a special case of SCP:



$$\mathbb{E}[\beta | \sigma^2, z] = m^{(1)} = \frac{n^{(0)}}{n^{(0)} + n} \mathbb{E}[\beta | \sigma^2] + \frac{n}{n^{(0)} + n} \hat{\beta}^{\text{LS}}$$

$$\mathbb{V}(\beta | \sigma^2, z) = \sigma^2 \mathbf{M}^{(1)} = \sigma^2 \frac{n}{n^{(0)} + n} (\mathbf{X}^\top \mathbf{X})^{-1}$$



CCCP: Update step for σ^2

Again, for the posterior on β it holds that

$$\mathbb{E}[\beta \mid z] = m^{(1)}$$

$$\mathbb{V}(\beta \mid z) = \mathbb{E}[\sigma^2 \mid z] \cdot M^{(1)}$$

such that the update step for $\mathbb{E}[\sigma^2]$ is of most interest:



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$$\mathbb{E}[\sigma^2 \mid z] = \frac{n^{(0)} + p}{n^{(0)} + n + p} \mathbb{E}[\sigma^2] + \frac{n - p}{n^{(0)} + n + p} \hat{\sigma}_{\text{LS}}^2 + \frac{p}{n^{(0)} + n + p} \hat{\sigma}_{\text{PDC}}^2$$

$$\hat{\sigma}_{\text{PDC}}^2 = \frac{1}{p} (\textcolor{brown}{m}^{(0)} - \hat{\beta}^{\text{LS}})^T \frac{n^{(0)}}{n^{(0)} + n} \mathbf{X}^T \mathbf{X} (\textcolor{brown}{m}^{(0)} - \hat{\beta}^{\text{LS}}) \quad \left[\mathbb{E}[\cdot \mid \sigma^2] = \sigma^2 \right]$$

For CCCP, two other interesting decompositions of $\mathbb{E}[\sigma^2 \mid z]$ exist.



CCCP: Summary

$$\mathbb{E}[\beta \mid z] = m^{(1)} = \frac{n^{(0)}}{n^{(0)} + n} \mathbb{E}[\beta \mid \sigma^2] + \frac{n}{n^{(0)} + n} \hat{\beta}^{\text{LS}}$$



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elements
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may increase
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elements
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$$= \frac{n^{(0)} + p}{n^{(0)} + n + p} \frac{n^{(0)}}{n^{(1)}} \underbrace{\mathbb{E}[\sigma^2] \frac{n}{n^{(0)}} (\mathbf{X}^\top \mathbf{X})^{-1}}_{\mathbb{V}(\beta)}$$

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$$+ \frac{n - p}{n^{(0)} + n + p} \frac{n}{n^{(1)}} \underbrace{\hat{\sigma}_{\text{LS}}^2 (\mathbf{X}^\top \mathbf{X})^{-1}}_{\mathbb{V}(\hat{\beta}^{\text{LS}})}$$

$$+ \frac{p}{n^{(0)} + n + p} \frac{n}{n^{(1)}} \underbrace{\hat{\sigma}_{\text{PDC}}^2 (\mathbf{X}^\top \mathbf{X})^{-1}}_{\mathbb{V}(\hat{\beta}^{\text{PDC}})}$$



Generalized Bayesian Inference: Basic Idea

Use **set of** priors → base inferences on **set of** posteriors obtained by element-wise updating



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Use **set of** priors → base inferences on **set of** posteriors
obtained by element-wise updating
→ numbers become intervals, e.g.

$$\mathbb{E}[\theta] \rightarrow [\underline{\mathbb{E}}[\theta], \bar{\mathbb{E}}[\theta]] = \left[\min_{p \in \mathcal{M}_\theta} \mathbb{E}_p[\theta], \max_{p \in \mathcal{M}_\theta} \mathbb{E}_p[\theta] \right]$$

$$P(\theta \in A) \rightarrow [\underline{P}(\theta \in A), \bar{P}(\theta \in A)] = [\min P_p(\theta \in A), \max P_p(\theta \in A)]$$



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$$P(\theta \in A) \rightarrow [\underline{P}(\theta \in A), \bar{P}(\theta \in A)] = [\min P_p(\theta \in A), \max P_p(\theta \in A)]$$

Shorter intervals ↔ more precise probability statements

Lottery A

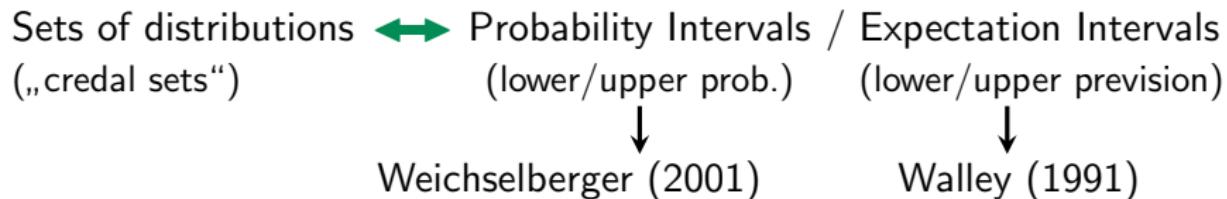
Number of winning tickets:
 exactly known as 5 out of 100
 → $P(\text{win}) = 5/100$

Lottery B

Number of winning tickets:
 not exactly known, supposedly
 between 1 and 7 out of 100
 → $P(\text{win}) = [1/100, 7/100]$

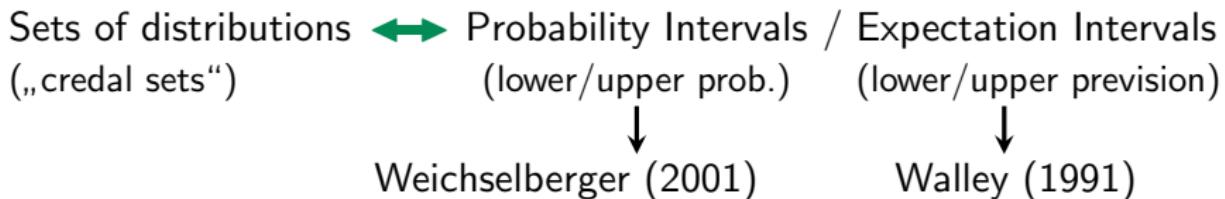


Generalized Bayesian Inference: Basic Idea





Generalized Bayesian Inference: Basic Idea

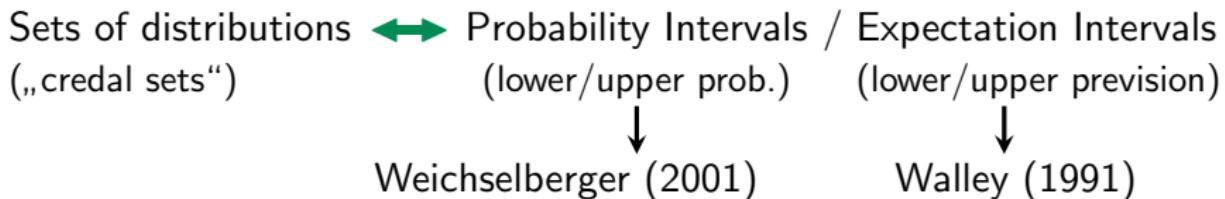


$$\overline{P}(A) = 1 - \underline{P}(A^c)$$

$$\overline{\mathbb{E}}[X] = -\underline{\mathbb{E}}(-X)$$



Generalized Bayesian Inference: Basic Idea

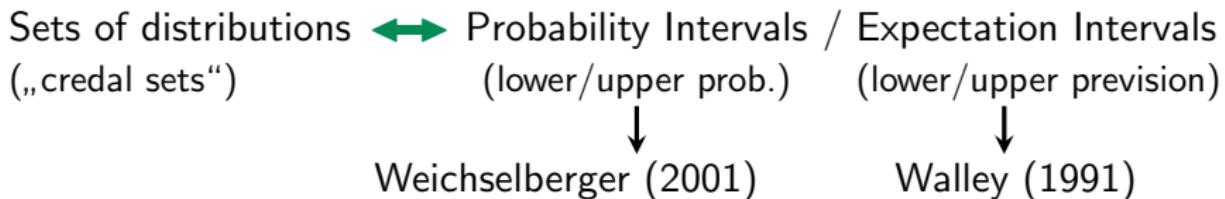


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→ The Society for Imprecise Probability: Theories and Applications
(ISIPTA conferences, summer schools, . . . www.sipta.org)



Generalized Bayesian Inference: Basic Idea

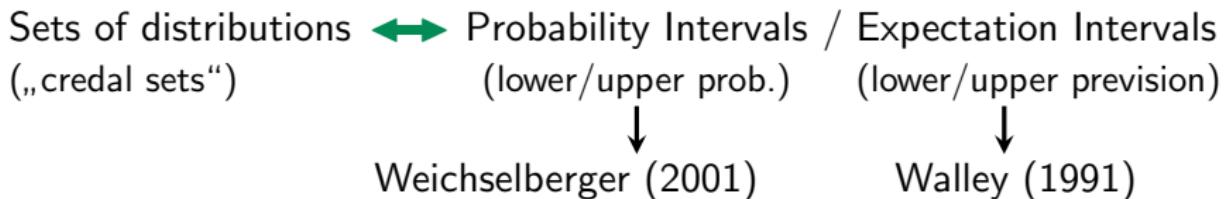


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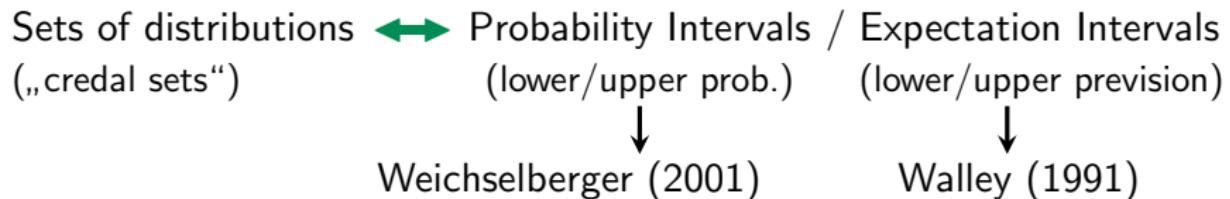


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$$\overline{P}(A) = 1 - \underline{P}(A^c) \qquad \overline{\mathbb{E}}[X] = -\underline{\mathbb{E}}(-X)$$

→ The Society for Imprecise Probability: Theories and Applications
 (ISIPTA conferences, summer schools, . . . www.sipta.org)

- Frank Coolen (my host)
- Thomas Augustin (my advisor)
- ...



Generalized iLUCK-models

Model for Bayesian inference with sets of priors
(Walter & Augustin, 2009)

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3. set of posteriors $\hat{=}$ set of (element-wise) updated priors
➡ still easy to handle: described as set of $(y^{(1)}, n^{(1)})$'s

$$y^{(1)} = \frac{n^{(0)}}{n^{(0)} + n} \cdot y^{(0)} + \frac{n}{n^{(0)} + n} \cdot \frac{1}{n} \tau(x)$$

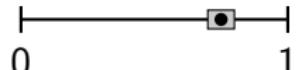
$$n^{(1)} = n^{(0)} + n$$



Generalized iLUCK-models: Simple Example

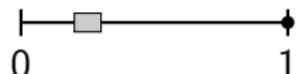
Case (i):

$$y_j^{(0)} \in [0.7, 0.8], \quad k_j/n = 0.75 \\ (n^{(0)} \in [1, 8]) \quad (n = 16)$$



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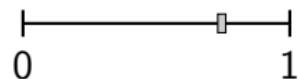


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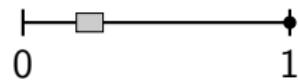
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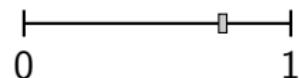


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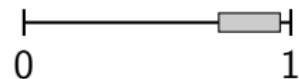
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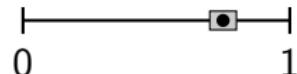




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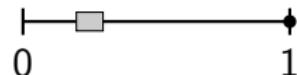


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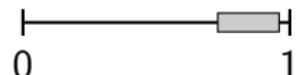


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Generalized iLUCK-models lead to cautious inferences
if, and only if, caution is needed.



Generalized iLUCK-models in Bayesian Linear Regression

- Apply generalized iLUCK-models to Bayesian linear regression in order to improve behaviour!



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 - update step has dimension-individual sensitivity to prior-data conflict, i.e. interval lengths in different dimensions depend on degree of prior-data conflict in that dimension.



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- ▶ Set interval for $\mathbb{E}[\sigma^2]$. (Update step is a bit tricky, though.)



Summary & References

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Walter, G., Augustin, T.: Bayesian linear regression — different conjugate models and their (in)sensitivity to prior-data conflict. In: Kneib, T., Tutz, G. (eds.), *Statistical Modelling and Regression Structures – Festschrift in the Honour of Ludwig Fahrmeir*, 2010.



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